

Solvable Integration Problems and Optimal Sample Size Selection

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(joint work with Erich Novak and Daniel Rudolf)



Special Session: When to stop a simulation

MCQMC2018, mercredi, le 4 juillet 2018, Rennes

Standard Monte Carlo integration

Task: Compute $\mathbb{E} Y$ from random samples $Y_1, Y_2, \dots \stackrel{\text{iid}}{\sim} Y$.

Standard Monte Carlo method:

$$\widehat{M}_n(Y) := \frac{1}{n} \sum_{i=1}^n Y_i$$

Application to **integration** w.r.t. prob. measure π on domain G , using $X, X_1, X_2, \dots \stackrel{\text{iid}}{\sim} \pi$:

$$\text{INT } f := \int_G f \, d\pi \approx \widehat{M}_n(f(X)) = \frac{1}{n} \sum_{i=1}^n f(X_i)$$

Standard Monte Carlo error / root mean square error (RMSE):

$$e(\widehat{M}_n, Y) := \sqrt{\mathbb{E} \left(\widehat{M}_n(Y) - \mathbb{E} Y \right)^2} = \frac{\sigma(Y)}{\sqrt{n}}$$

Problem: What if **variance** $\sigma^2(Y)$ unknown?

Integration for a-priori unknown variance

Theorem (Hickernell, Jiang, Liu, Owen 2013)

Given $K > 1$, then for any *error threshold* $\varepsilon > 0$ and any *uncertainty level* $\delta > 0$, there exists an algorithm $A_{\varepsilon, \delta}^K$ such that

$$\mathbb{P} \left\{ |A_{\varepsilon, \delta}^K(Y) - \mathbb{E} Y| > \varepsilon \right\} \leq \delta$$

for all Y with *bounded kurtosis*, $\|Y - \mathbb{E} Y\|_4 \leq K \|Y - \mathbb{E} Y\|_2$.

Idea:

- ① use fixed sample Y_1, \dots, Y_{n_1} for a variance estimate
- ② choose size n_2 of sample $Y_{n_1+1}, \dots, Y_{n_1+n_2}$ for mean estimate

There is no solution with fixed sample size!

Question: Optimality? *Other assumptions?* Mean squared error?

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Definition of solvability

Inputset $\mathcal{F} \subset L_1(\pi)$ — class of integrands f
with respect to prob. measure π on domain G

General randomized algorithm = mapping $A : \Omega \times \mathcal{F} \rightarrow \mathbb{R}$,
requiring only finitely many function evaluations, $n(\omega, f) < \infty$.

Special type: **i.i.d.-based algorithms** using $f(X_i)$ where $X_i \stackrel{\text{iid}}{\sim} \pi$

Definition (Solvable integration problems)

The integration problem is **solvable** for \mathcal{F}
iff for all $\varepsilon, \delta > 0$ exists an (ε, δ) -**approximating** algorithm A , i.e.

$$\mathbb{P} \{ |A(f) - \text{INT } f| > \varepsilon \} \leq \delta \quad \text{for all } f \in \mathcal{F}.$$

Example of an unsolvable problem

Theorem (K., Novak, Rudolf 2018)

The integration problem $\int_0^1 f \, dx$
is *unsolvable* for the class $\mathcal{F} = C^\infty([0, 1])$.

Idea of the proof: How would you distinguish $f = 0$
from functions f with huge integral but small support? **Impossible!**

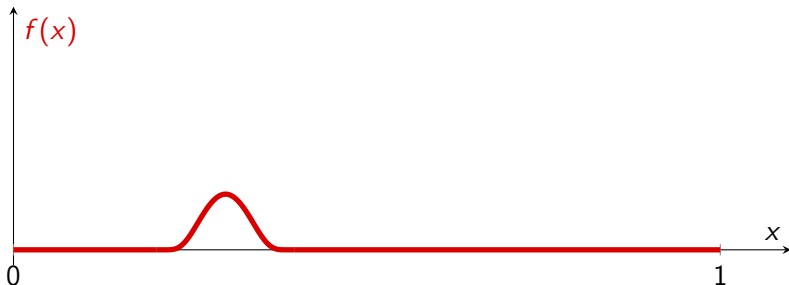


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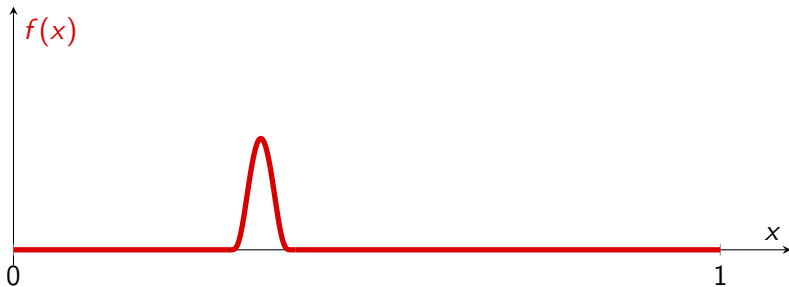


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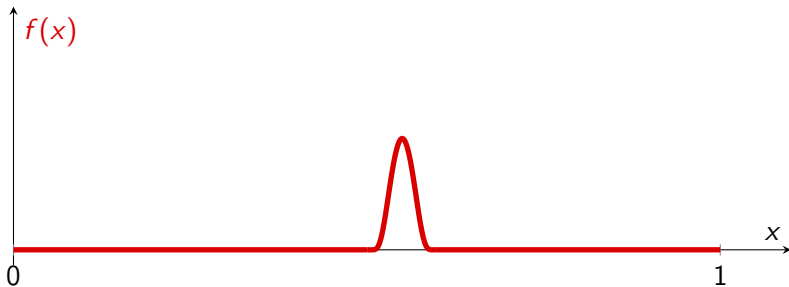


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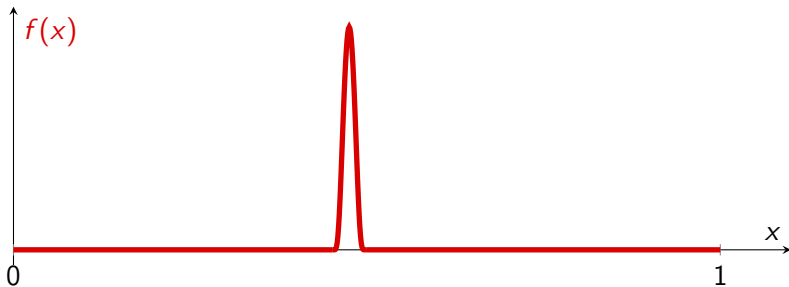


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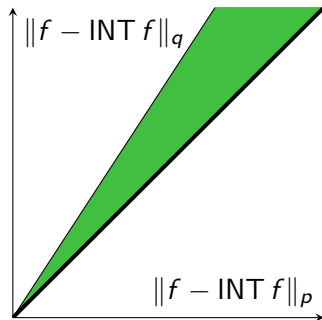


Generalizing the kurtosis – a cone-shaped input set

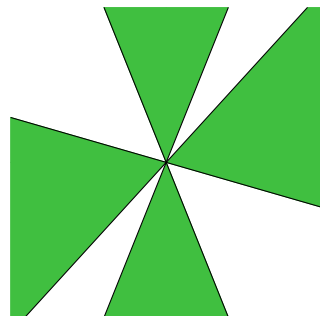
For $1 \leq p < q \leq \infty$ and $K > 1$, (Hickernell et al.: $p = 2, q = 4$)

$$\mathcal{F}_{p,q,K} := \{f \in L_q(\pi) : \|f - \text{INT } f\|_q \leq K \|f - \text{INT } f\|_p\}$$

Scaling property: $f \in \mathcal{F}_{p,q,K} \Rightarrow cf \in \mathcal{F}_{p,q,K}$ for all $c \in \mathbb{R}$.



cone condition



within 2-dim. subspace of L_q

Upper bound for the expected cost

Recall input set for $1 \leq p < q \leq \infty$ and $K > 1$,

$$\mathcal{F}_{p,q,K} := \{f \in L_q(\pi) : \|f - \text{INT } f\|_q \leq K \|f - \text{INT } f\|_p\}$$

Theorem (K, Novak, Rudolf 2018)

For any *error threshold* $\varepsilon > 0$ and *uncertainty level* $\delta > 0$, there exists an (ε, δ) -approximating algorithm $A_{\varepsilon, \delta}^{p,q,K}$ on $\mathcal{F}_{p,q,K}$. Writing $\tilde{q} := \min\{q, 2\}$, the *expected sample size* \bar{n} is bounded by

$$\begin{aligned} \bar{n}(A_{\varepsilon, \delta}^{p,q,K}, f) &:= \mathbb{E} n(\omega, f) \\ &\leq \left[C_q K^{pq/(q-p)} + C_{q,K} \left(\frac{\|f - \text{INT } f\|_1}{\varepsilon} \right)^{1+1/(\tilde{q}-1)} \right] \log \frac{1}{\delta}. \end{aligned}$$

Structure of the algorithm

Parameters: odd $k, k' \in \mathbb{N}$; $2 \leq m \in \mathbb{N}$; $1 < \eta \in \mathbb{R}$.

Information: random samples $Y_i := f(X_i)$ with $X_1, X_2, \dots \stackrel{\text{iid}}{\sim} \pi$

- ① estimate $\|f - \text{INT } f\|_1$ from $n_1 := k \cdot m$ observations:

$$\hat{R}_{k,m} := \text{med}(\hat{R}_m^{(1)}, \dots, \hat{R}_m^{(k)}), \quad \text{where}$$

$$\hat{R}_m^{(\ell)} \stackrel{\text{iid}}{\sim} \frac{1}{m} \sum_{i=1}^m |Y_i - \hat{M}_m|, \quad \text{with} \quad \hat{M}_m := \frac{1}{m} \sum_{i=1}^m Y_i$$

- ② estimate $\text{INT } f$ via $n_2 := k' \cdot m'$ additional observations,
 $m' := \max\{\lceil \eta (\hat{R}_{k,m})^{1+1/(\tilde{q}-1)} \rceil, 1\}$, with $\tilde{q} := \min\{q, 2\}$,

$$A_{k,m}^{k',\eta,\tilde{q}}(f) := \text{med}(\tilde{M}_{m'}^{(1)}, \dots, \tilde{M}_{m'}^{(k')}), \quad \text{where} \quad \tilde{M}_{m'}^{(\ell)} \stackrel{\text{iid}}{\sim} \hat{M}_{m'}$$

Median trick \leadsto probability amplification, finite expected cost

Alternative for ① on $\mathcal{F}_{p,q,K}$: if $q \leq 2$, estimate $\|f - \text{INT } f\|_p^p$,
 if $2 < q$, estimate $\|f - \text{INT } f\|_2^2$.

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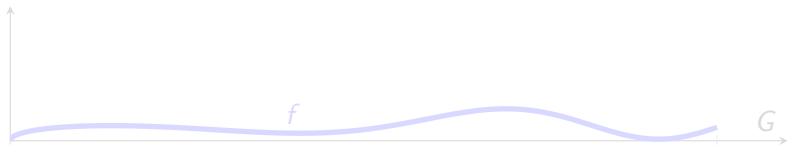
An absolute lower bound – the fixed cost

Theorem (K, Novak, Rudolf 2018)

Any (ε, δ) -approximating algorithm $A_{\varepsilon, \delta}$ on $\mathcal{F}_{p, q, K}$ requires a minimal amount of information, irrespective of the input,

$$\begin{aligned} \bar{n}^{\text{fix}}(\varepsilon, \delta, \mathcal{F}_{p, q, K}) &:= \inf_{A_{\varepsilon, \delta}} \inf_{f \in \mathcal{F}_{p, q, K}} \bar{n}(A_{\varepsilon, \delta}, f) \\ &\geq \frac{1}{2 \log 2} K^{pq/(q-p)} \log \frac{1}{2\delta}. \end{aligned}$$

Proof: Distinguish $f \in \mathcal{F}_{p, q, K}$ from perturbed $f + h \in \mathcal{F}_{p, q, K}$, where $h \in \mathcal{F}_{p, q, K}$ with $\pi\{h = c\} = 1 - \pi\{h = 0\} \in (0, \frac{1}{2})$?



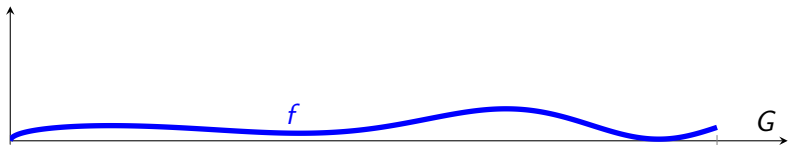
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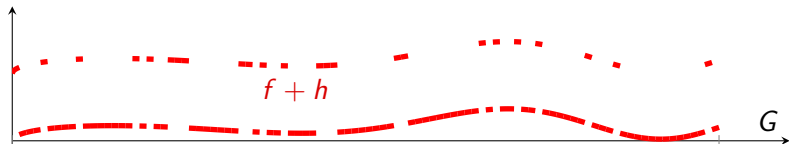
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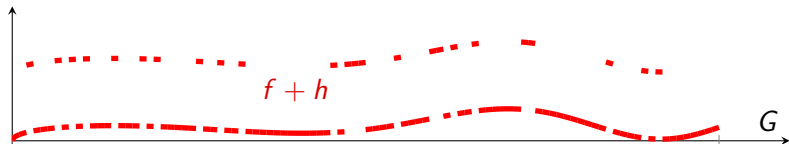
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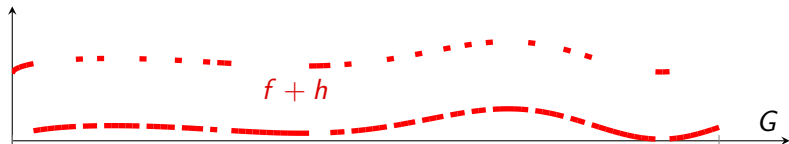
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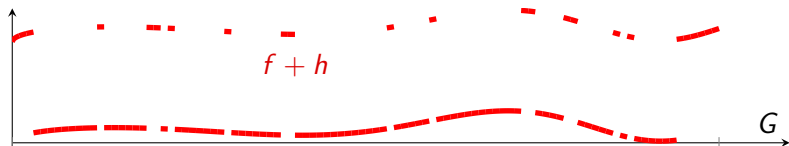
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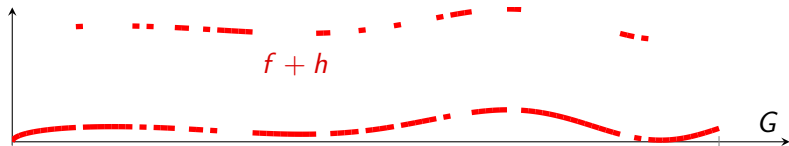
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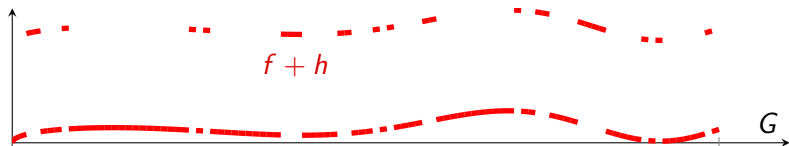
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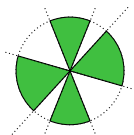
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Worst case cost for bounded norm

Put $\tilde{q} := \min\{q, 2\}$, we intersect $\mathcal{F}_{p,q,K}$ with

$$\tau\mathcal{B}_{\tilde{q}} := \{f \in L_{\tilde{q}}(\pi) : \|f - \text{INT } f\|_{\tilde{q}} \leq \tau\}$$



Theorem (K, Novak, Rudolf 2018)

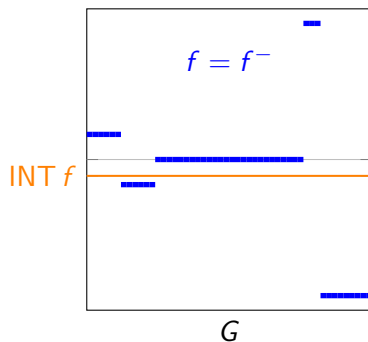
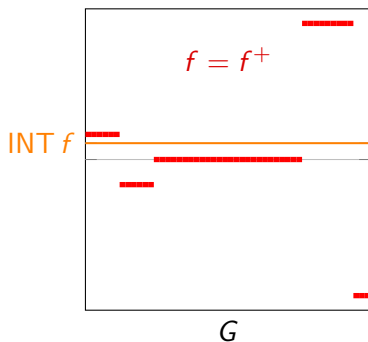
For any (ε, δ) -approximating algorithm $A_{\varepsilon, \delta}$ on $\mathcal{F}_{p,q,K}$, the worst case cost for $\|f - \text{INT } f\|_{\tilde{q}} \leq \tau$ is bounded below by

$$\begin{aligned} \bar{n}^{\text{wor}}(\varepsilon, \delta, \mathcal{F}_{p,q,K} \cap \tau\mathcal{B}_{\tilde{q}}) &:= \inf_{A_{\varepsilon, \delta}} \sup_{f \in \mathcal{F}_{p,q,K} \cap \tau\mathcal{B}_{\tilde{q}}} \bar{n}(A_{\varepsilon, \delta}, f) \\ &\geq c_{q,K} \left(\frac{\tau}{\varepsilon}\right)^{1+1/(\tilde{q}-1)} \log \frac{3}{4\delta} \end{aligned}$$

for error thresholds $0 < \varepsilon < C_K \tau$ and uncertainty $0 < \delta \leq \frac{1}{4}$.

Worst case cost for bounded norm – proof

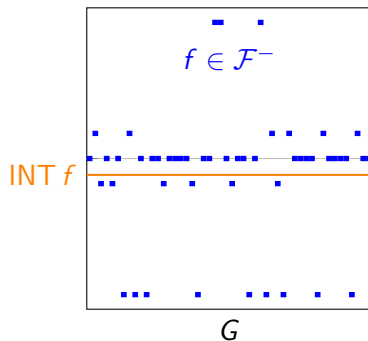
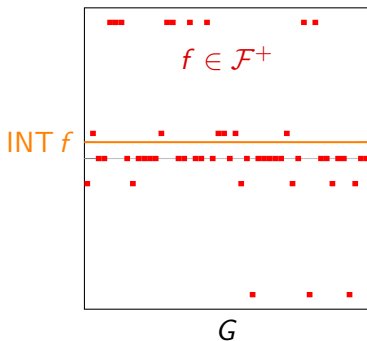
Worst case lower bounds on $\mathcal{F}_{p,q,K} \cap \tau\mathcal{B}_{\tilde{q}}$ using i.i.d. $Y_i := f(X_i)$ via cost bounds for statistical tests (Wald 1945) $\rightsquigarrow f^+$ vs. f^- ?



Same lower bounds for general algorithms using function values, if π has no atoms \rightsquigarrow distinguish shuffled classes \mathcal{F}^+ and \mathcal{F}^-

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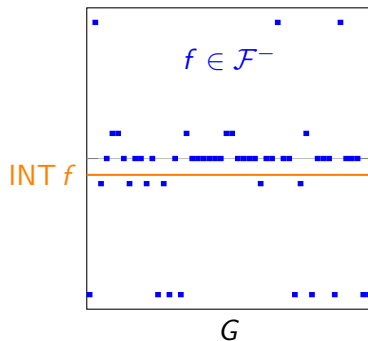
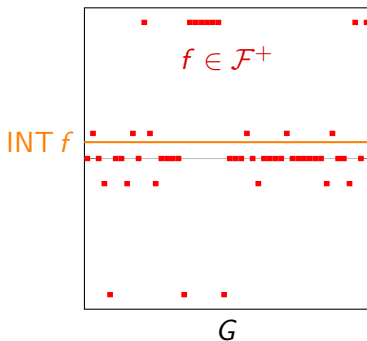
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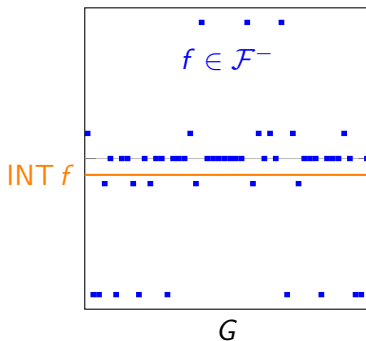
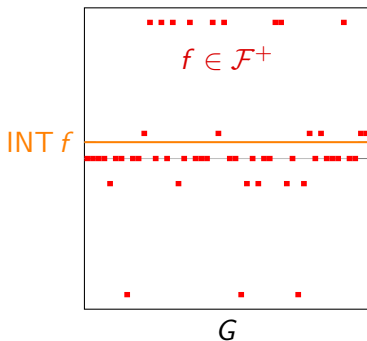
Worst case lower bounds on $\mathcal{F}_{p,q,K} \cap \tau\mathcal{B}_{\tilde{q}}$ using i.i.d. $Y_i := f(X_i)$ via cost bounds for statistical tests (Wald 1945) $\rightsquigarrow f^+$ vs. f^- ?



Same lower bounds for general algorithms using function values, if π has no atoms \rightsquigarrow distinguish shuffled classes \mathcal{F}^+ and \mathcal{F}^-

Worst case cost for bounded norm – proof

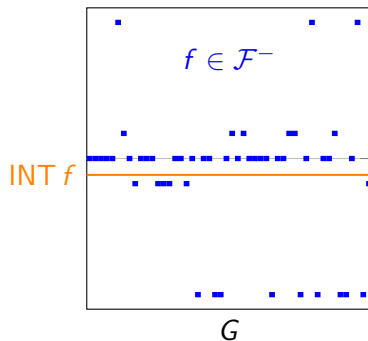
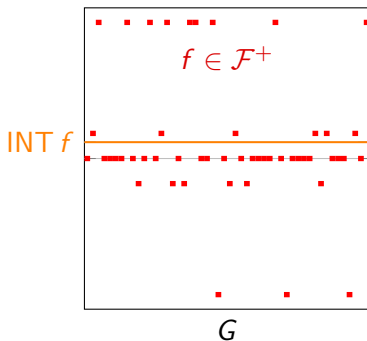
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Same lower bounds for general algorithms using function values, if π has no atoms \rightsquigarrow distinguish shuffled classes \mathcal{F}^+ and \mathcal{F}^-

Summary

Input set for $1 \leq p < q \leq \infty$ and $K > 1$, $\tilde{q} := \min\{q, 2\}$

$$\mathcal{F}_{p,q,K} := \{f \in L_q(\pi) : \|f - \text{INT } f\|_q \leq K \|f - \text{INT } f\|_p\}$$

Upper bound for (ε, δ) -approximating algorithm $A_{\varepsilon,\delta}^{p,q,K}$ on $\mathcal{F}_{p,q,K}$

$$\bar{n}(A_{\varepsilon,\delta}^{p,q,K}, f) \leq C_{q,K} \left[1 + \left(\frac{\|f - \text{INT } f\|_1}{\varepsilon} \right)^{1+1/(\tilde{q}-1)} \right] \log \frac{1}{\delta}$$




Fixed cost – an absolute lower bound

$$\bar{n}^{\text{fix}}(\varepsilon, \delta, \mathcal{F}_{p,q,K}) \geq \frac{1}{2 \log 2} K^{pq/(q-p)} \log \frac{1}{2\delta}$$

Worst case cost for $\|f - \text{INT } f\|_{\tilde{q}} \leq \tau$,

$$\bar{n}^{\text{wor}}(\varepsilon, \delta, \mathcal{F}_{p,q,K} \cap \tau \mathcal{B}_{\tilde{q}}) \geq c_{q,K} \left(\frac{\tau}{\varepsilon} \right)^{1+1/(\tilde{q}-1)} \log \frac{3}{4\delta}$$

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