

# Feynman–Kac models

*Stability & discretization*

**MCQMC 2018**

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# Situation

If *this meeting* is about

$x$  – Monte Carlo

with

$x \in \{ \text{Quasi, Markov Chain, Sequential, Quantum, Hamiltonian, Multilevel, Diffusion, Langevin, Multifidelity...} \},$

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then *this talk* would be on

$x$  – Monte Carlo,

with

$x \in \{ \text{Sequential, Quantum, Diffusion} \},$

summarized as *Feynman–Kac models* (also known as splitting, genealogical, branching models, etc).

## Motivation

## Ergodicity for Markov chains

## Ergodicity for Feynman–Kac dynamics

## A word on discretization

## Conclusion

## A rare event problem

- Consider a dynamics over  $\mathcal{X} \subset \mathbb{R}^d$ :

$$dX_t = b(X_t)dt + \sigma(X_t)dB_t,$$

with invariant measure  $\mu$  and generator  $\mathcal{L}$ .

- Ergodicity: for a test function  $f$

$$\frac{1}{t} \int_0^t f(X_s) ds \xrightarrow{t \rightarrow +\infty} \int_{\mathcal{X}} f(x) \mu(dx).$$

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- Idea of *large deviations*:

$$\mathbb{P} \left[ \frac{1}{t} \int_0^t f(X_s) ds = a \right] \asymp e^{-tI(a)},$$

where  $I$  is the *rate function*, or *generalized entropy creation*.

# Duality and importance sampling

- Donsker-Varadhan duality [70's]: in many cases it holds

$$I(a) = \sup_{k \in \mathbb{R}} \{ka - \lambda_f(k)\},$$

where

$$\lambda_f(k) = \lim_{t \rightarrow \infty} \frac{1}{t} \log \mathbb{E} \left[ e^{k \int_0^t f(X_s) ds} \right].$$

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- Similar to study, for an observable  $\varphi$ ,

$$\Theta_t(\mu)(\varphi) = \frac{\mathbb{E}_\mu \left[ \varphi(X_t) e^{\int_0^t f(X_s) ds} \right]}{\mathbb{E}_\mu \left[ e^{\int_0^t f(X_s) ds} \right]}.$$

- This procedure *weights the trajectories* depending on  $f$ .



# Natural questions

One may wonder:

- for which class of functions  $f$  does  $\lambda_f$  exists?
- under which conditions  $\Theta_t$  admits a long time limit?
- how can we discretize in time for numerical purposes?
- how to sample efficiently the expectations?

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## Link with filtering & Sequential Monte Carlo

In Sequential Monte Carlo/filtering, we generally consider the weighted path measure

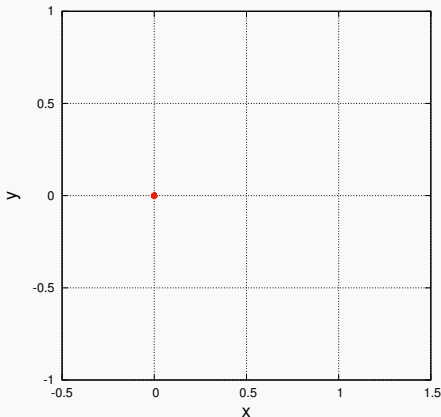
$$\mathbb{Q}_n(dx_{0:n}) = \frac{1}{L_n} \left\{ G_0(x_0) \prod_{k=1}^t G_k(x_{k-1}, x_k) \right\} \mathbb{M}_0(dx_0) \prod_{k=1}^n M_k(x_{k-1}, x_k).$$

Analogies:

- $G_k(x_{k-1}, x_k) \leftrightarrow e^{f(x_{k-1})}$  with «potential»  $f$ ,
- $M_k \leftrightarrow Q(x, \cdot) = \mathbb{E}[x_k \in \cdot \mid x_{k-1} = x]$  homogeneous transition kernel,
- $L_n \leftrightarrow (e^f Q)^n \mathbf{1} = \mathbb{E}[e^{\sum_{k=0}^{n-1} f(x_k)}]$  accumulated weight up to time  $n$  (sometimes written  $\gamma_n(1)$ ).

# Numerics – Sequential Monte Carlo

- Dynamics  $(x_{n+1}, y_{n+1}) = (x_n, y_n) - 0.1(x_n, y_n) + G_n \in \mathbb{R}^2$ ,
- Weight function  $f(x, y) = x$ .



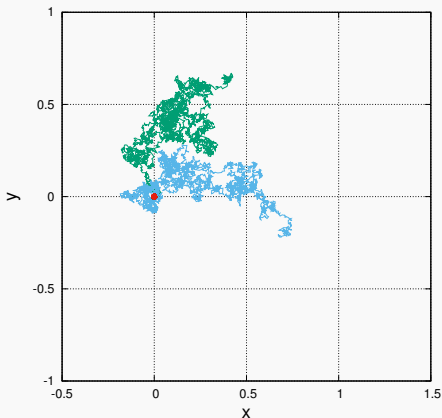
The weight

$$w_m^n = \exp \left( \sum_{k=0}^{n-1} f(x_k^m) \right).$$

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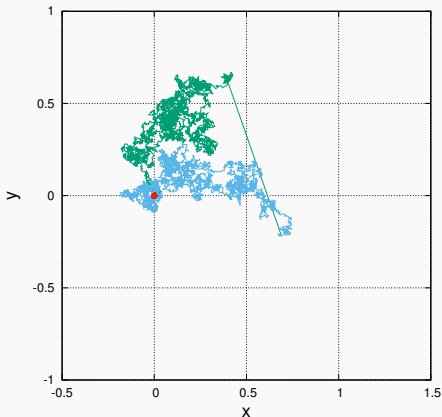
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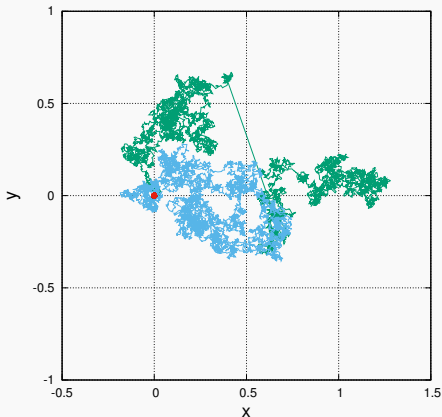
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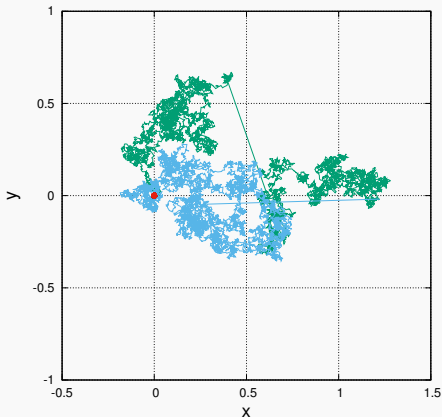
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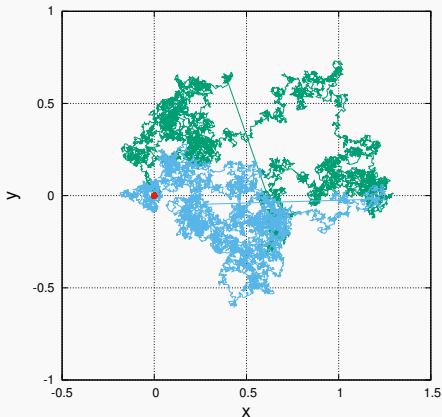
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**Conclusion:** the particles are selected towards the right.

Motivation

**Ergodicity for Markov chains**

Ergodicity for Feynman–Kac dynamics

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# Markov chains and ergodicity

A homogeneous Markov chain  $(x_n)_{n \in \mathbb{N}}$  is defined through its *evolution operator*  $Q$ :

$$Q\varphi(x) := \mathbb{E}[\varphi(x_1) \mid x_0 = x] = \int_{\mathcal{X}} \varphi(y) Q(x, dy).$$

A measure  $\mu^* \in \mathcal{P}(\mathcal{X})$  is *invariant* if  $\forall A \subset \mathcal{X}$ :

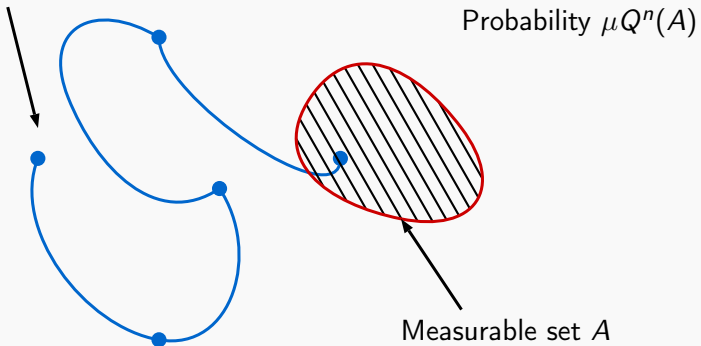
$$\mu^* Q(A) := \int_{\mathcal{X}} \mu^*(dx) Q(x, A) = \mu(A).$$

The process is *ergodic* when, for any initial distribution  $\mu$ ,

$$\mu Q^n \xrightarrow{n \rightarrow +\infty} \mu^*.$$

# Big picture I

Trajectory of the Markov chain



# An ergodic theorem

## Theorem [M. Hairer & J. Mattingly]

Assume there exist  $W : \mathcal{X} \rightarrow \mathbb{R}_+$ ,  $\gamma \in (0, 1)$  and  $C > 0$  such that

$$(L) \quad PW \leq \gamma W + C,$$

and  $\alpha > 0$ ,  $\eta \in \mathcal{P}(\mathcal{X})$  such that

$$(M) \quad \inf_{x \in \mathcal{C}} P(x, \cdot) \geq \alpha \eta(\cdot),$$

for  $\mathcal{C}$  a large enough level set of  $W$ . Then, there exist a unique  $\mu^* \in \mathcal{P}(\mathcal{X})$ ,  $C > 0$  and  $\bar{\alpha} \in (0, 1)$  such that for any  $\mu \in \mathcal{P}(\mathcal{X})$

$$\|P^n \mu - \mu^*\|_W \leq C \bar{\alpha}^n \|\mu - \mu^*\|_W.$$

Here:  $\|f\| = \sup_{x \in \mathcal{X}} \frac{|f(x)|}{1 + W(x)}$ ,  $\|\mu - \nu\|_W = \sup_{\|\varphi\| \leq 1} \int_{\mathcal{X}} \varphi(x) (\mu - \nu)(dx)$ .

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Ergodicity for Markov chains

**Ergodicity for Feynman–Kac dynamics**

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# Feynman–Kac models

We consider:

- a kernel operator  $Q^f$  with  $Q^f \neq \mathbb{1}$ ;
- a dynamics  $\Phi_n : \mathcal{P}(\mathcal{X}) \rightarrow \mathcal{P}(\mathcal{X})$  defined by, for tests functions  $\varphi$

$$\Phi_n(\mu)(\phi) = \frac{\mu((Q^f)^n \varphi)}{\mu((Q^f)^n \mathbb{1})} = (\Phi^n)(\mu)(\varphi) \quad \text{with} \quad \Phi(\mu)(\varphi) = \frac{\mu(Q^f \varphi)}{\mu(Q^f \mathbb{1})}.$$

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Typically

- $Q^f = e^f Q$ , where  $Q$  defines a Markov chain  $(x_n)_{n \in \mathbb{N}}$ ;
- then

$$\Phi_n(\mu)(\phi) = \frac{\mathbb{E}_\mu \left[ \varphi(x_n) e^{\sum_{k=0}^{n-1} f(x_k)} \right]}{\mathbb{E}_\mu \left[ e^{\sum_{k=0}^{n-1} f(x_k)} \right]}.$$



# Ergodicity for Feynman–Kac dynamics

## Theorem [G.F., M. Rousset & G. Stoltz, yesterday]

Assumptions:

- Lyapunov condition: there exist  $W : \mathcal{X} \rightarrow [1, +\infty)$ ,  $\gamma_n \xrightarrow{\infty} 0$ ,  $b_n \geq 0$  and compact sets  $K_n$  s.t.

$$(L) \quad Q^n W(x) \leq \gamma_n W(x) + b_n \mathbb{1}_{K_n};$$

- Minorization condition:  $\forall n \geq 1$ , there exist  $\alpha_n > 0$ ,  $\eta_n \in \mathcal{P}(\mathcal{X})$  s.t.

$$(M) \quad \forall x \in K_n, \quad Q^n(x, \cdot) \geq \alpha_n \eta_n(\cdot);$$

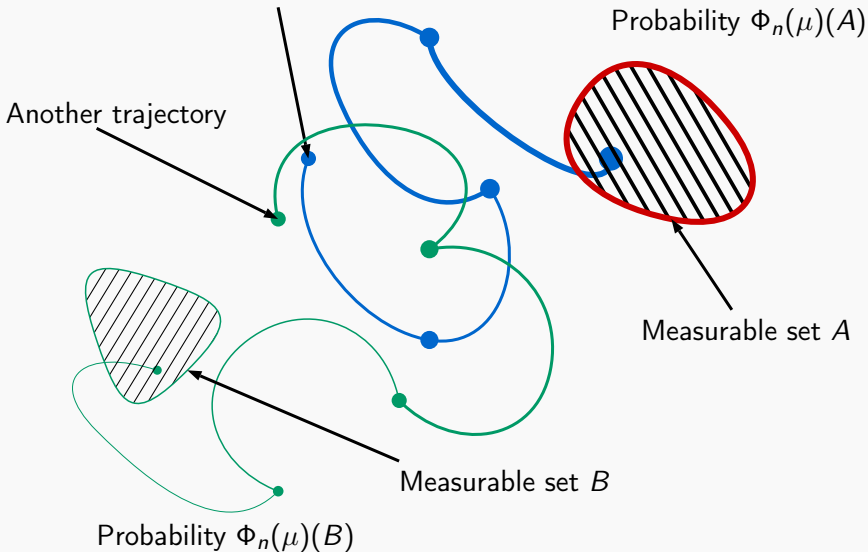
- $\mathcal{X}$  is Polish and  $Q^n$  is «locally strong Feller».

Then, there exist a unique  $\mu_f^*$  and  $\bar{\alpha} \in (0, 1)$  such that for any  $\mu \in \mathcal{P}(\mathcal{X})$ ,  $\exists C_\mu > 0$  for which

$$\|\Phi_n(\mu) - \mu_f^*\|_W \leq C_\mu \bar{\alpha}^n, \quad \text{and} \quad \Phi(\mu_f^*) = \mu_f^*.$$

# Big picture II

A trajectory of the Markov chain



## Sketch of proof

The steps of the proof are as follows:

- $Q^f$  is quasi-compact in  $L_W^\infty(\mathcal{X}) = \{\varphi : \sup |\varphi|/W < +\infty\}$ ;
- the spectral radius  $\Lambda$  is an eigenvalue with «positive» eigenvector  $h$ :

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- define the *Markovian* kernel  $Q_h = \Lambda h^{-1} Q^f h$ ;
- $\Phi_n$  is rewritten

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## Toy model application

Consider the following Markov chain in  $\mathbb{R}^d$ :

$$x_{n+1} = \rho x_n + \sigma G_n,$$

with  $\rho \in (-1, 1)$ ,  $(G_n)_{n \in \mathbb{N}}$  standard Gaussian r.v.

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*Then*, the Feynman–Kac dynamics is stable if

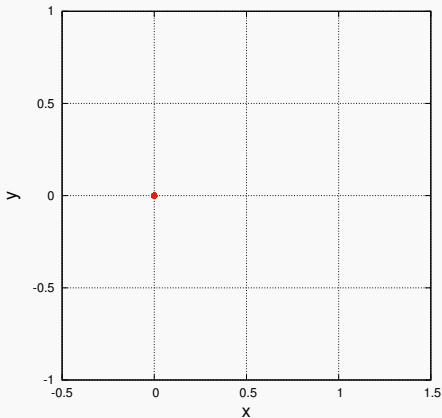
$$f(x) \leq a|x|^p + c,$$

with  $a > 0$ ,  $c \in \mathbb{R}$ , and  $0 \leq p < 2$ . The *Lyapunov function* is

$$W(x) = e^{\beta x^2}, \quad \text{with } 0 < \beta < \frac{1 - \rho^2}{2\sigma^2}.$$

## Back to O.U. process

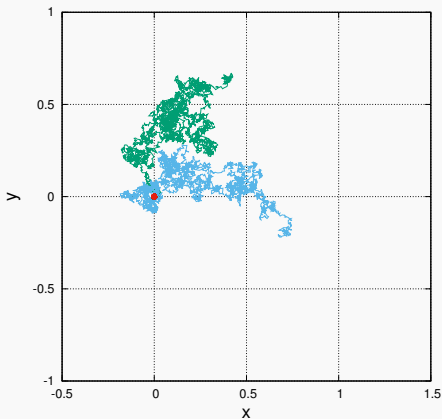
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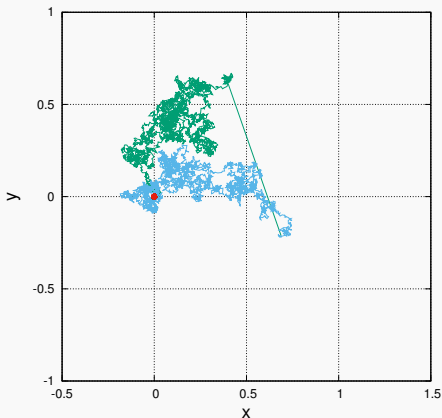
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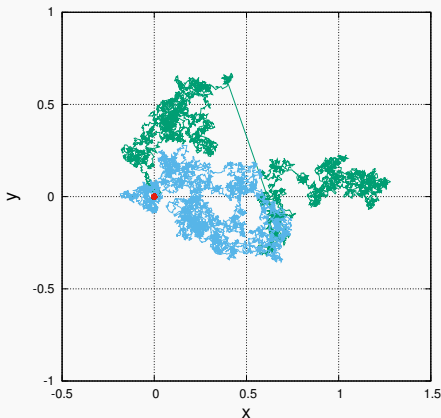
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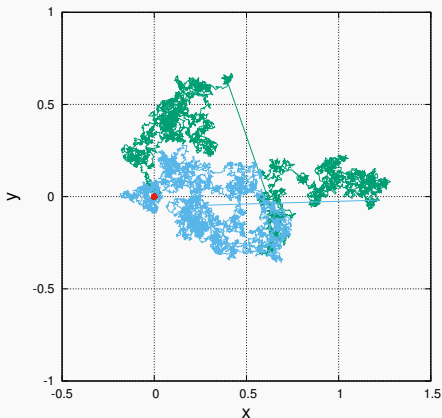


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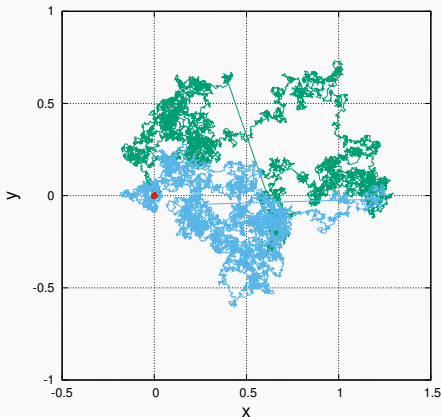


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Goal: discretize in time the quantity

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*Idea:* discretize  $(X_t)$  into  $x_n \approx X_{n\Delta t}$ , and consider e.g.

$$\Phi_{n,\Delta t}(\mu)(\phi) = \frac{\mathbb{E}_\mu \left[ \varphi(x_n) e^{\sum_{k=0}^{n-1} f(x_k) \Delta t} \right]}{\mathbb{E}_\mu \left[ e^{\sum_{k=0}^{n-1} f(x_k) \Delta t} \right]}.$$

Other possible choice:

$$\Phi_{n,\Delta t}(\mu)(\phi) = \frac{\mathbb{E}_\mu \left[ \varphi(x_n) e^{\sum_{k=0}^{n-1} \frac{f(x_k) + f(x_{k+1})}{2} \Delta t} \right]}{\mathbb{E}_\mu \left[ e^{\sum_{k=0}^{n-1} \frac{f(x_k) + f(x_{k+1})}{2} \Delta t} \right]}.$$



## Discretization

Under *verifiable conditions* and if  $\mathcal{X}$  is bounded, the following theorem holds.

**Theorem: error estimate on the invariant measure [G.F., G. Stoltz, 2017]**

There exist  $\mu_f^*, \mu_{f,\Delta t}^* \in \mathcal{P}(\mathcal{X})$  such that  $\forall \mu \in \mathcal{P}(\mathcal{X})$

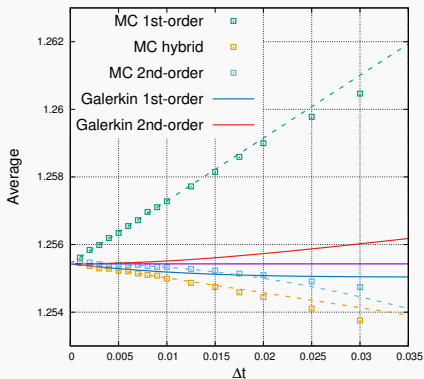
$$\Theta_t(\mu) \xrightarrow{t \rightarrow +\infty} \mu_f^*, \quad \Phi_n(\mu) \xrightarrow{n \rightarrow +\infty} \mu_{f,\Delta t}^*.$$

Moreover, there exist  $p \geq 1$  and  $\psi$  solution to a Poisson equation such that

$$\int_{\mathcal{X}} \varphi d\mu_{f,\Delta t}^* = \int_{\mathcal{X}} \varphi d\mu_f^* + \Delta t^p \int_{\mathcal{X}} \varphi \psi d\mu_f^* + O(\Delta t^{p+1}).$$

# Application

Overdamped Langevin dynamics on a one dimensional torus.



Average estimate for:

- $dX_t = (-V'(X_t) + 1)dt + dB_t$ ,
- $V(x) = 0.02 \cos(2\pi x)$ ,
- $f = |V|^2$ ,
- $\varphi = e^f$
- Euler-Maruyama scheme and 2nd order modified scheme,
- comparison to Galerkin discretization.

# Conclusion

Take home message:

- new results on the ergodicity of Feynman–Kac dynamics;
- easily verifiable conditions;
- natural extension of the theory for Markov chains;
- numerical analysis for discretizations of SDE's;
- possible directions: applications to SPDE's, link with large deviations theory, application to systems of interacting particles...

# References



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Yet another look at Harris' ergodic theorem for Markov chains.

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**Luc Rey-Bellet.**

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# Spectrum of quasi-compact operators

